PANA ACADEMY

NEPAL ENGINEERING COUNCIL
LICENSE EXAM PREPARATION COURSE

FOR

CIVIL ENGINEERS

3. Basic Water Resources Engineering

3.2 Hydrostatics

Sub topics

PANA ACADEMY

- pressure and head
- Pascal’s law
- pressure-depth relationship
- Manometers
- pressure force and centre of pressure on submerged bodies (plane and curved surfaces, practical applications)
- pressure diagrams
- Buoyancy
- stability of floating/submerged bodies.

Pressure

Pressure (P) is the force applied perpendicular to the surface of an object per unit area.

$$P = \frac{F}{A} = \gamma h = \rho g h$$

Unit: Pa, N/m^2

1 atm =101325 Pa =1.01325 bar

1 bar = 10^5 Pa

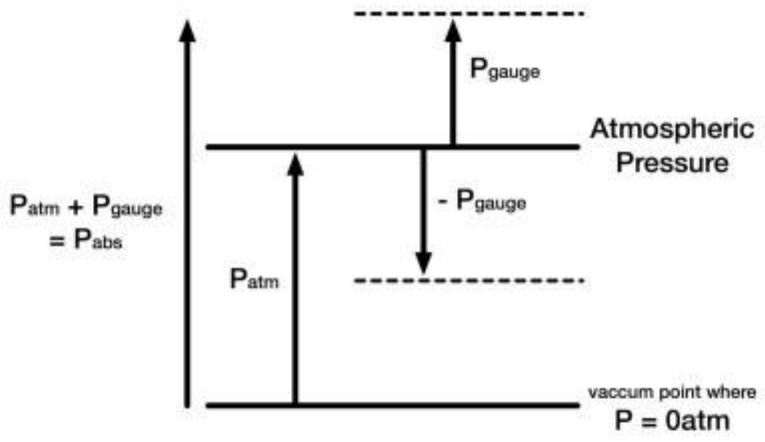
Atmospheric pressure decreases about 10% while moving 1 km higher altitude

Pressure

Absolute Pressure: Absolute pressure is the sum of gauge pressure and atmospheric pressure.

Gauge Pressure: Gauge pressure is the pressure relative to atmospheric pressure.

Vacuum Pressure: Negative gauge Pressure



$$P_{abs} = P_g + P_{atm}$$

$$P_g = P_{abs} - P_{atm}, if\, P_{abs} > P_{atm}$$

$$P_v = P_{atm} - P_{abs}, if\, P_{abs} < P_{atm}$$

Pressure head

The pressure head is the height of a liquid column that corresponds to a particular pressure exerted by the liquid column on the base of its container. It may also be called **static pressure head** or simply **static head.**

$$\psi = \frac{p}{\gamma} = \frac{p}{\rho\, g}$$

Hydrostatic Law

According to Hydrostatic Law, the rate of increase of pressure in a vertical direction is equal to the weight density/ specific weight of the fluid at that point when the fluid is stationary.

$$\frac{\partial P}{\partial z} = \gamma$$

The pressure at any point in a fluid at rest is obtained by the Hydrostatic Law.

$$P_{abs} = P_{atm} + \gamma h$$

Hydrostatic Law

PANA ACADEMY

$$\frac{\partial P}{\partial z} = -\rho(a_z + g)$$

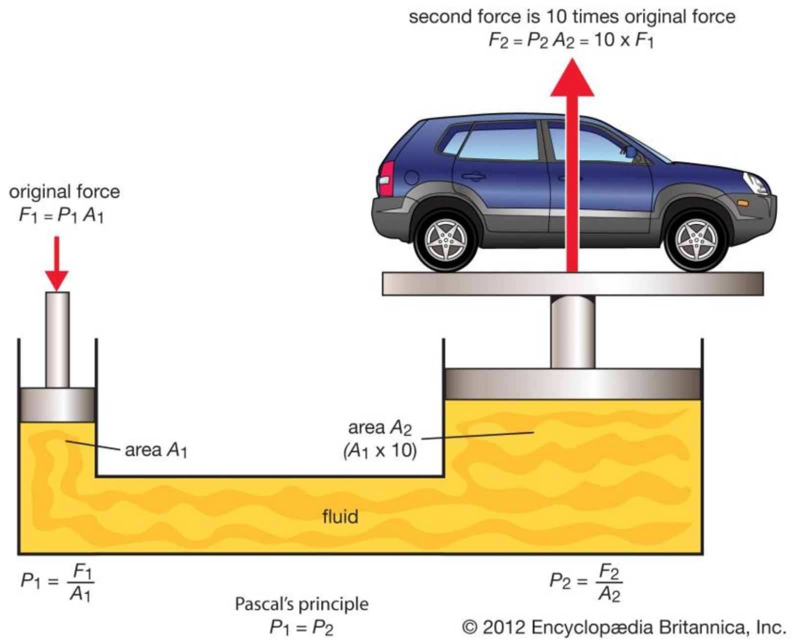
$$\frac{\partial P}{\partial x} = -\rho(a_x)$$

$$\frac{\partial P}{\partial y} = -\rho(a_y)$$

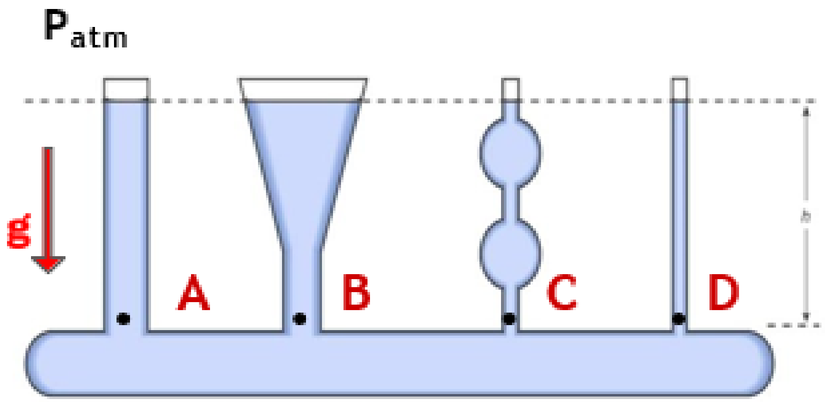
Pascal’s Law

PANA ACADEMY

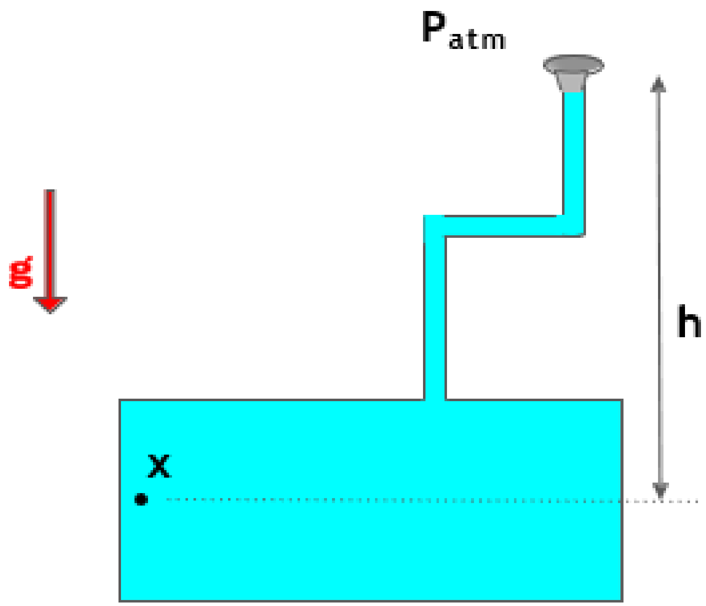
The external static pressure applied on a confined liquid is distributed or transmitted evenly throughout the liquid in all directions



Fluid Pressure does NOT depend on shape of Vessel



$P_A = P_B = P_C = P_D = P_{atm} + h\rho g$



$P_x = P_{atm} + h\rho g$

Pressure Measurement

PANA ACADEMY

Barometer

$$P_{atm} = P_v + \gamma h$$

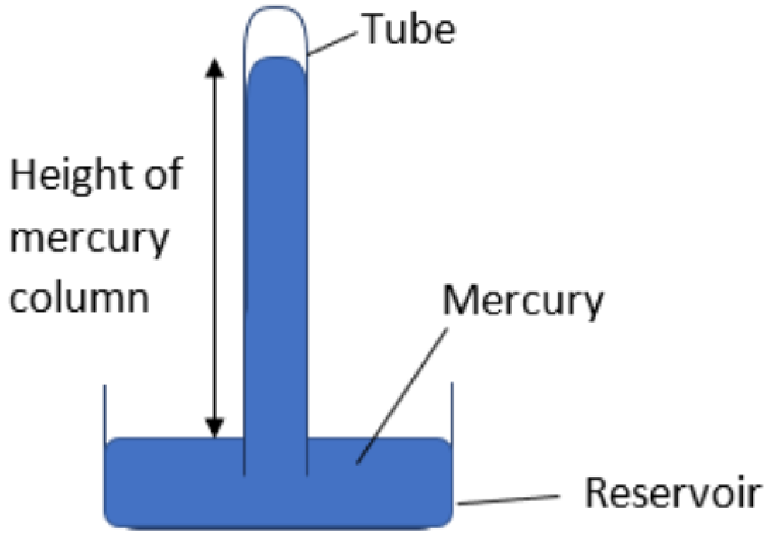
Mercury is suitable as it has very low vapour pressure such that

$$P_{atm} = \gamma h$$

It cannot measure negative gauge pressure

Pressure measured in mm of Hg

$$P_{atm} = 760\ mm\ of\ Hg = ?\ m\ of\ H_2O$$



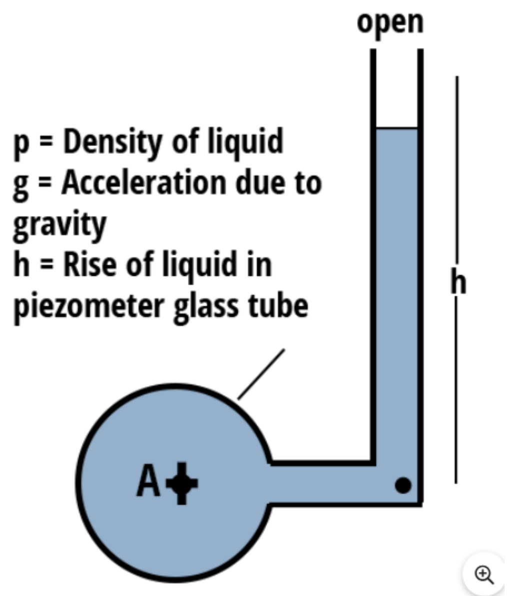
Pressure Measurement

Manometer

Mercury generally used as it is higher density liquid

Used for medium pressure liquid

$$P_A = P_{atm} + \gamma_m h$$



A Schematic Diagram of the Piezometer

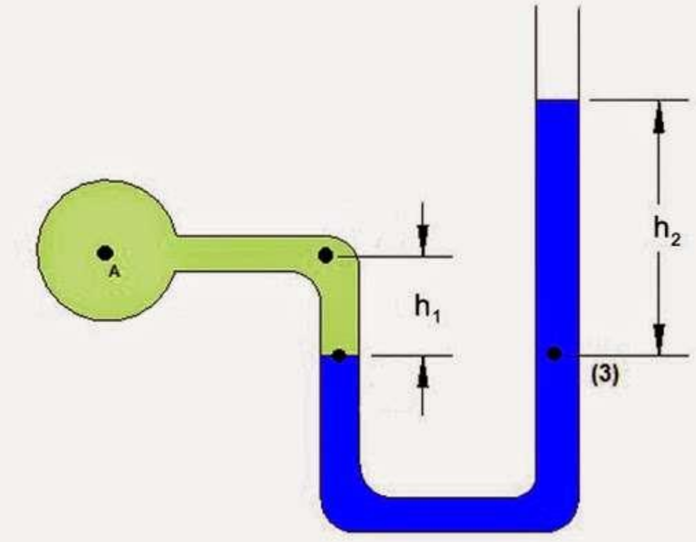
Pressure Measurement

Manometer

Mercury generally used as it is higher density liquid

$$P_3 = P_{atm} + \gamma_m h_2$$
$$P_3 = P_A + \gamma_l h_1$$

$$P_{atm} + \gamma_m h_2 = P_A + \gamma_l h_1$$
$$P_A = P_{atm} + \gamma_m h_2 - \gamma_l h_1$$



U - Tube Manometer

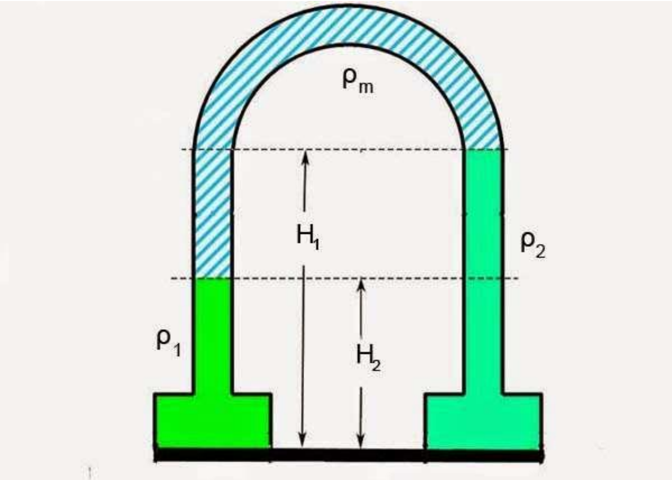
Pressure Measurement

Inverted U tube Manometer

$$P_A = P_2 + \rho_2 g(H_1)$$
$$P_B = P_2 + \rho_m g(H_1 - H_2) + \rho_1 g(H_2)$$

$$P_A - P_B = \rho_2 g(H_1) - \rho_m g(H_1 - H_2) - \rho_1 g(H_2)$$

Density of manometric fluid should be less than other liquid



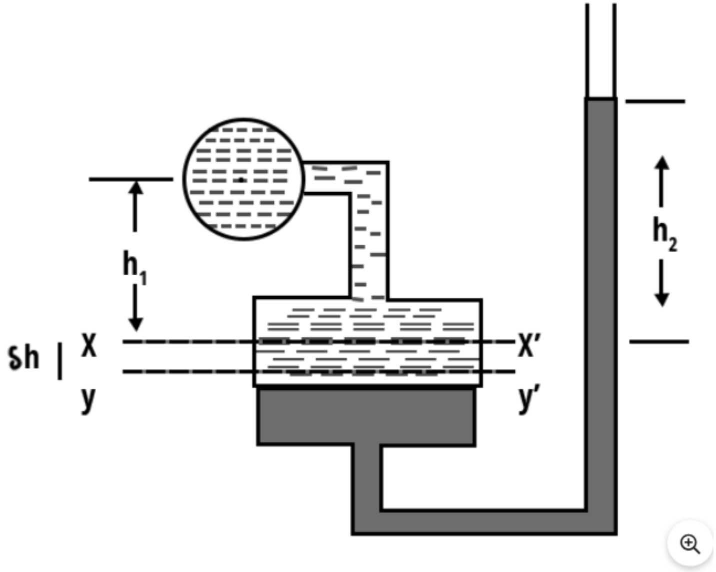
Inverted U tube Manometer

Pressure Measurement

PANA ACADEMY

Vertical single column Manometer

$$P_3 = \rho_m g(h_2 + \Delta h)$$
$$P_3 = P_A + \rho_l g(h_1 + \Delta h)$$
$$P_A = \rho_m g(h_2 + \Delta h) - \rho_l g(h_1 + \Delta h)$$
$$P_A \approx \rho_m g(h_2) - \rho_l g(h_1)$$



A Schematic Representation of a Vertical Single Column Manometer

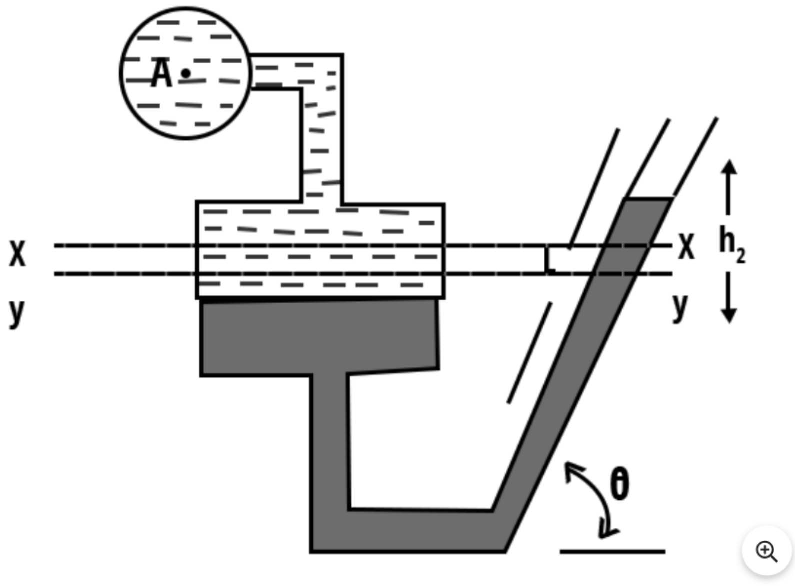
Pressure Measurement

PANA ACADEMY

Inclined single column Manometer

$$P_3 = \rho_m g sin\theta(h_2 + \Delta h)$$
$$P_3 = P_A + \rho_l g(h_1 + \Delta h)$$
$$P_A = \rho_m g sin\theta(h_2 + \Delta h) - \rho_l g(h_1 + \Delta h)$$
$$P_A \approx \rho_m g h_2 sin\theta - \rho_l g h_1$$

Error decreases and sensitivity increases by factor of $1/\sin\theta$



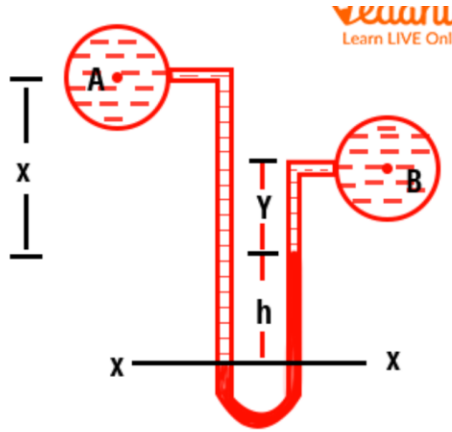
A Schematic Representation of Inclined Single Column Manometer

Pressure Measurement

PANA ACADEMY

U tube differential Manometer

$$P_A - P_B = hg\left(\rho_g - \rho_1\right) + \rho_2 gy - \rho_1 gx$$

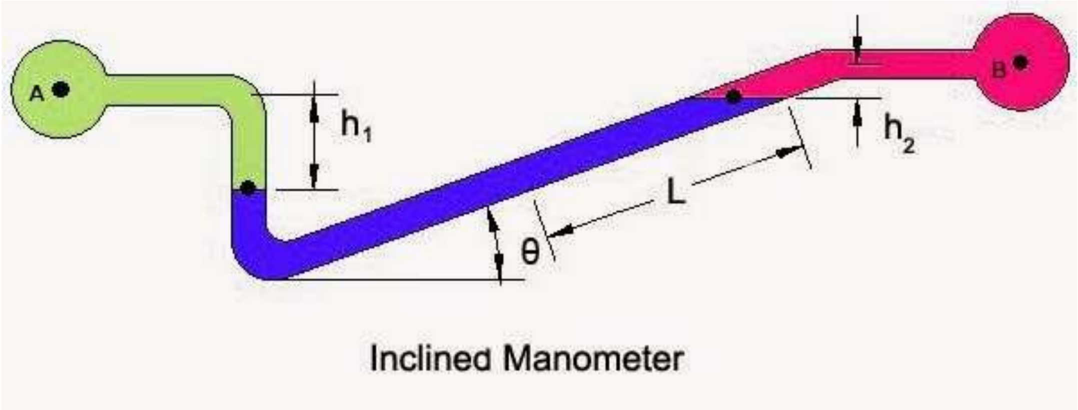


(a) Two pipes at different levels

A Schematic Representation of a Differential U-Tube Manometer

Pressure Measurement

Inclined U tube Manometer



Pressure Measurement

Double U tube Manometer

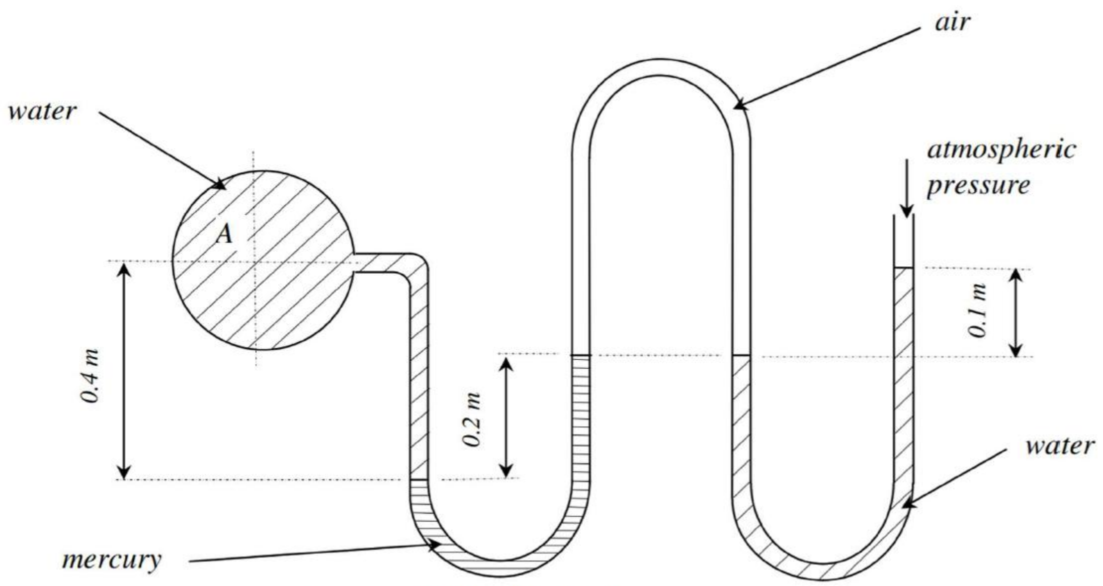


Figure Q1: Double U-tube manometer

Pressure Distribution

Pressure is compressive and acts normal to surface.

Pressure at top = 0

Pressure at bottom = γh

Average pressure = $\gamma h/2$

Force on wall per unit width = $\frac{1}{2}\gamma h^2$

Resultant force acts at $\frac{2}{3}h$ from free surface

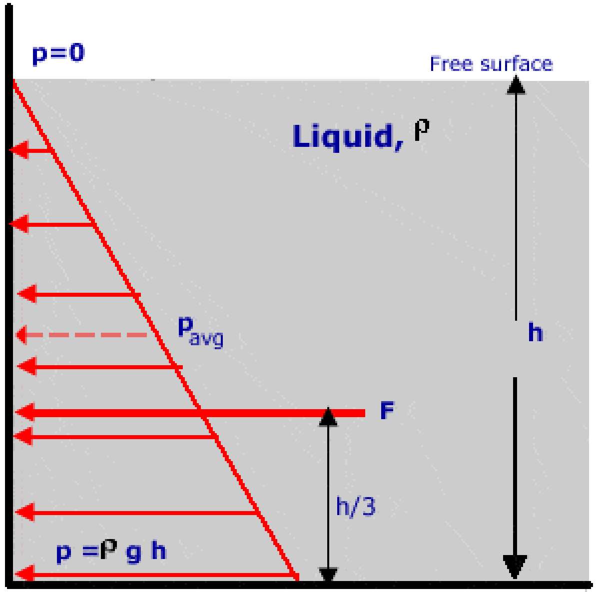


Figure: Pressure and Resultant Force on a Vertical Plane Surface

Pressure Distribution

Pressure is compressive and acts normal to surface.

Pressure at top = 0

Pressure at bottom = γh

Average pressure = $\gamma h/2$

Force on wall = $\gamma A\bar{x}$

Resultant force acts at $\bar{h}$ from free surface

$$\bar{h} = \bar{x} + \frac{I_{GG}\sin^2\theta}{A\bar{x}}$$

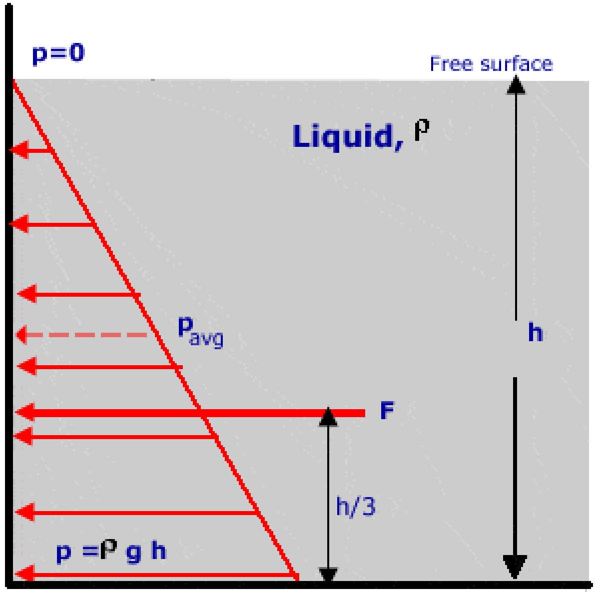


Figure: Pressure and Resultant Force on a Vertical Plane Surface

Pressure Distribution

PANA ACADEMY

Pressure is compressive and acts normal to surface.

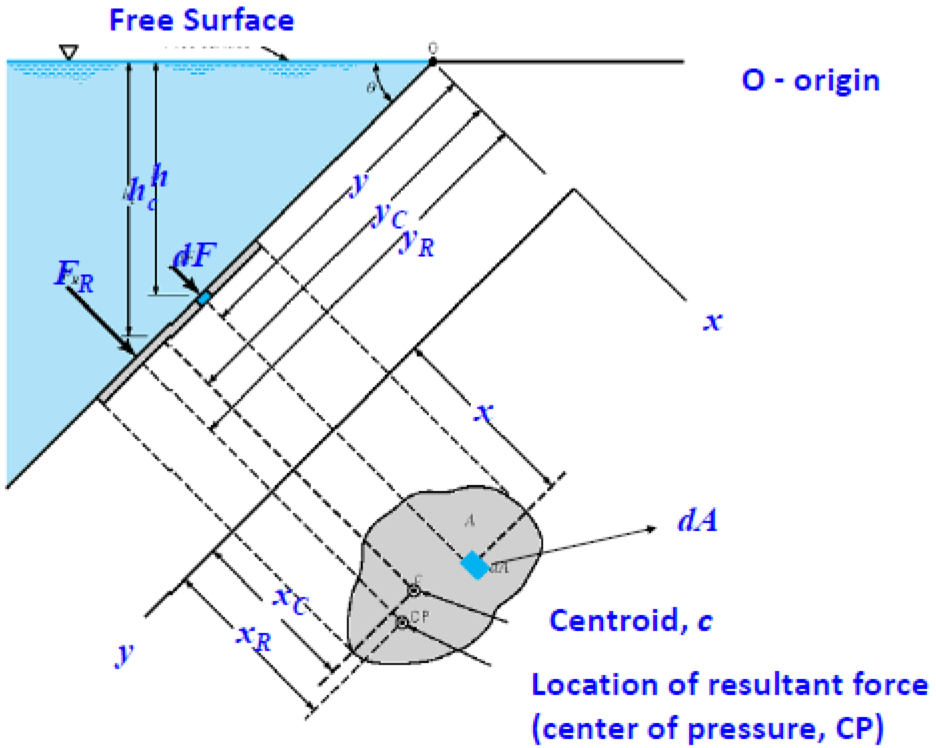
Pressure at top = γh_1

Pressure at bottom = γh_2

Force = $\gamma A \bar{x}$

Resultant force acts at $\bar{h}$ from free surface

$$\bar{h} = \bar{x} + \frac{I_{GG} \sin^2 \theta}{A\bar{x}}$$



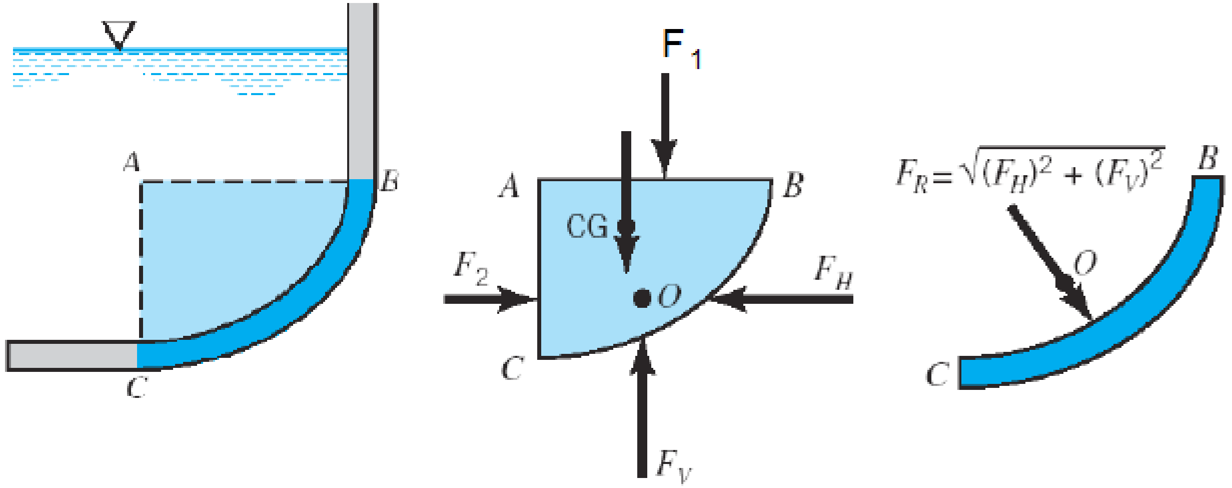
Pressure Distribution

Horizontal force component

Force = $\gamma A\bar{x}$

Resultant force acts at $\bar{h}$ from free surface

$$\bar{h} = \bar{x} + \frac{I_{GG}}{A\bar{x}}$$



Vertical force component

Force = wt. of liquid above the curved surface

Downward direction depends on wetting surface being inside area considered

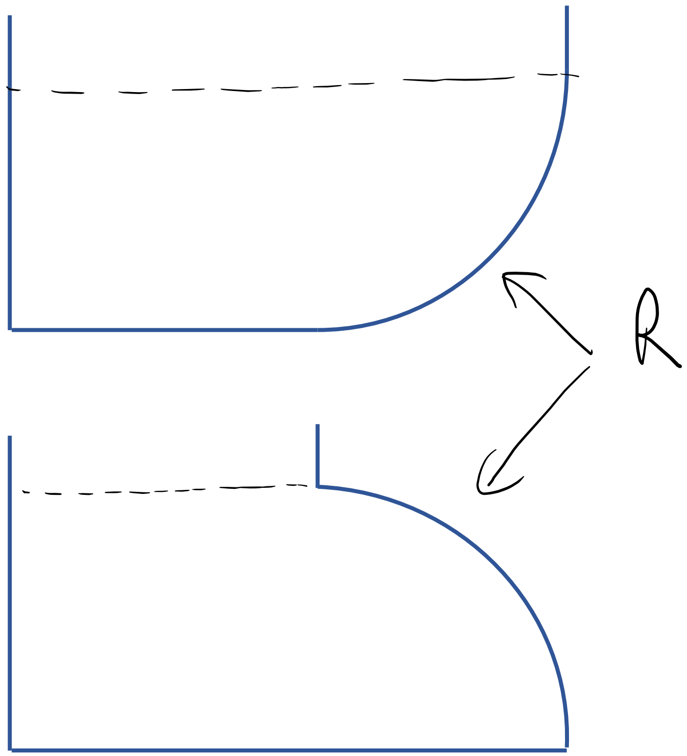
Pressure Distribution

Horizontal force component

Force = $\gamma A \bar{x}$

Resultant force acts at $\bar{h}$ from free surface

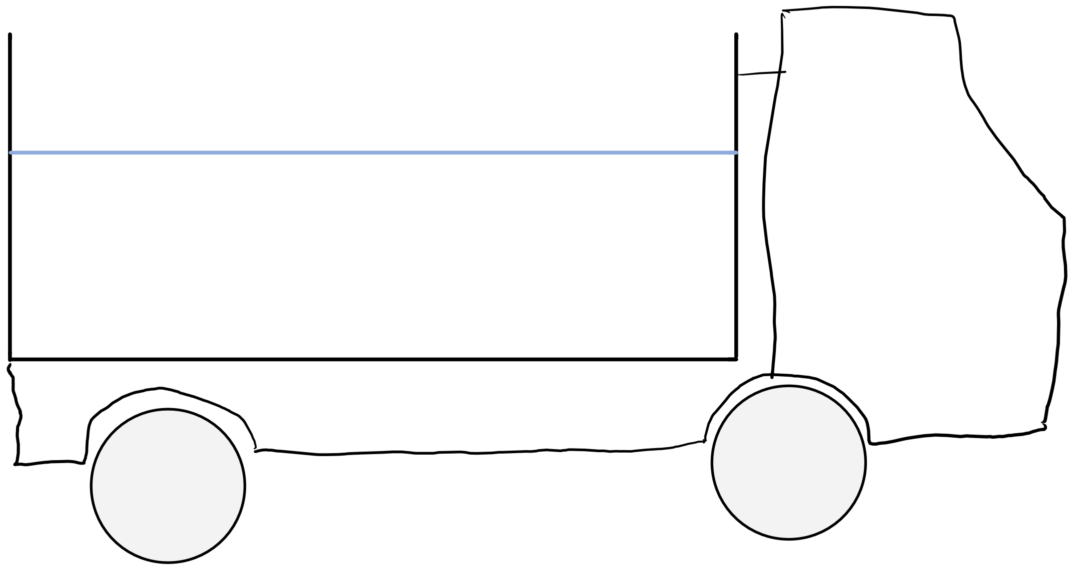
$$\bar{h} = \bar{x} + \frac{I_{GG}}{A\bar{x}}$$



Pressure Distribution

$$\frac{\partial P}{\partial z} = -\rho(a_z + g), \frac{\partial P}{\partial x} = -\rho(a_x), \frac{\partial P}{\partial y} = -\rho(a_y)$$

$$tan\theta = \frac{dz}{dx} = \frac{a_x}{a_z + g}$$

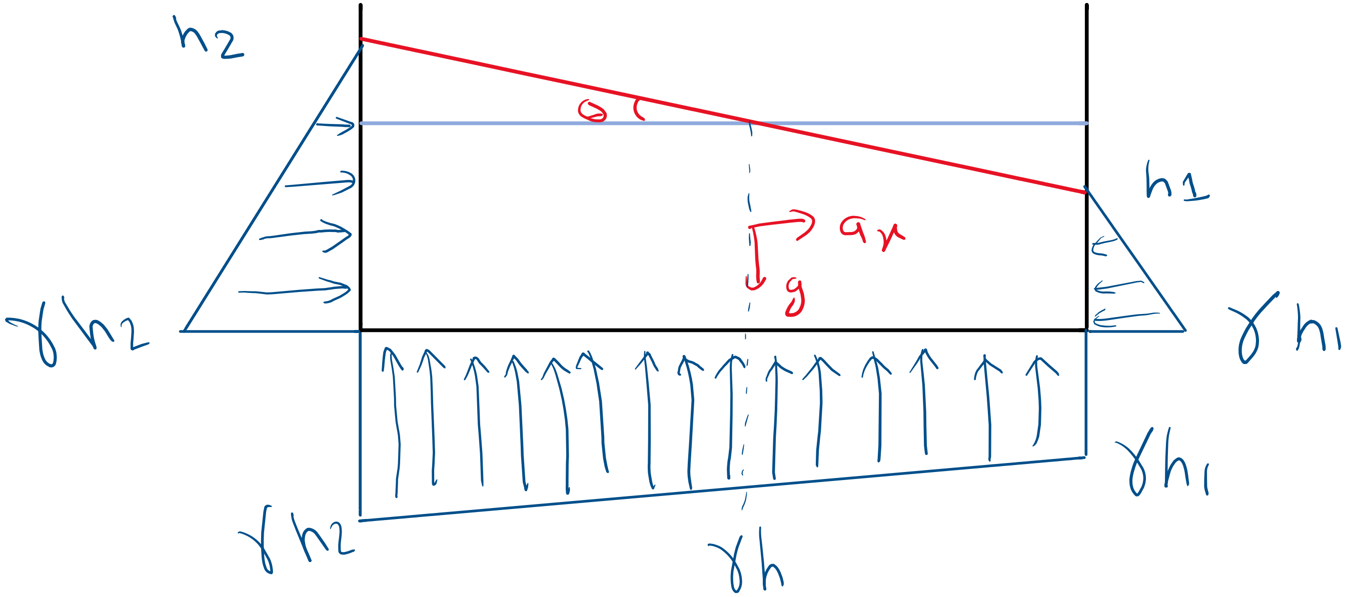


Pressure Distribution

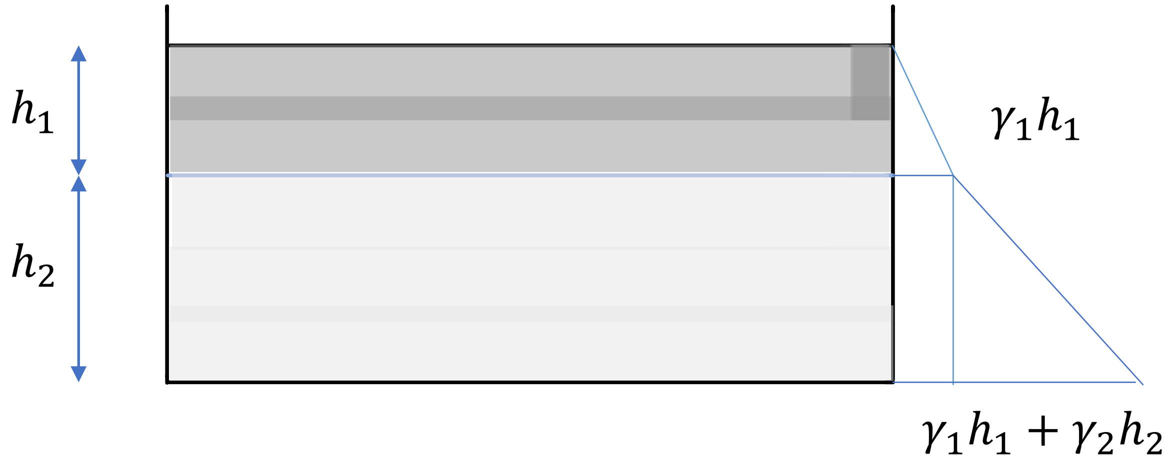
$$h_2 = h + \frac{L}{2} sin\theta$$

$$h_1 = h - \frac{L}{2} sin\theta$$

$$tan\theta = \frac{dz}{dx} = \frac{a_x}{g}$$



Pressure Distribution



Buoyancy

Buoyancy or upthrust, is an upward force exerted by a fluid that opposes the weight of a partially or fully immersed object.

Buoyancy

If $B < W$, Body sinks

Buoyancy

PANA ACADEMY

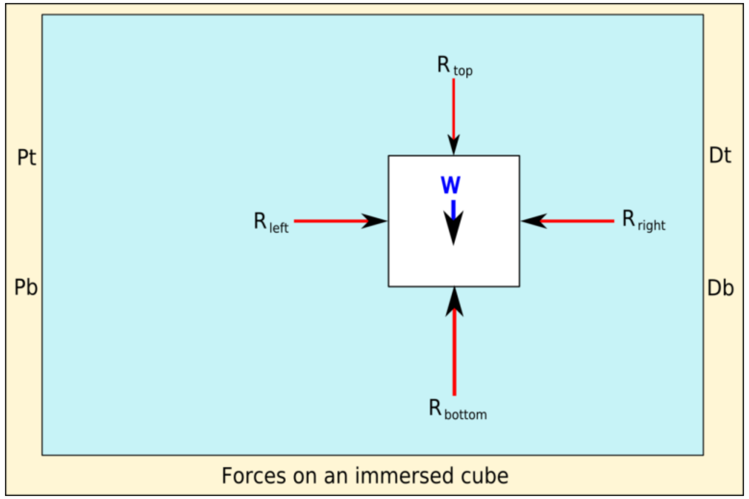
Buoyancy or upthrust, is an upward force exerted by a fluid that opposes the weight of a partially or fully immersed object.

If B < W, Body sinks

If B = W, Body floats, partially or fully immersed

Buoyancy = Weight of liquid displaced

And it acts at center of volume displaced



Forces on an immersed cube

Buoyancy

Buoyancy = Weight of liquid displaced

If V_{imm} be the volume of body submersed

Buoyancy = $\gamma_w V_{imm}$

For a floating body,

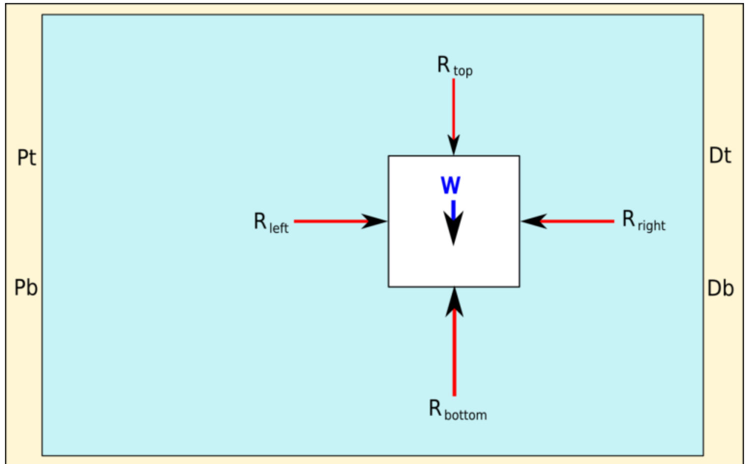
Buoyancy = Weight

$$\gamma_w V_{imm} = \gamma_m V$$

$$\frac{V_{imm}}{V} = \frac{\gamma_m}{\gamma_w}$$

Part of body submersed = $\frac{\gamma_m}{\gamma_w}$

Part of body outside water = $1 - \frac{\gamma_m}{\gamma_w}$



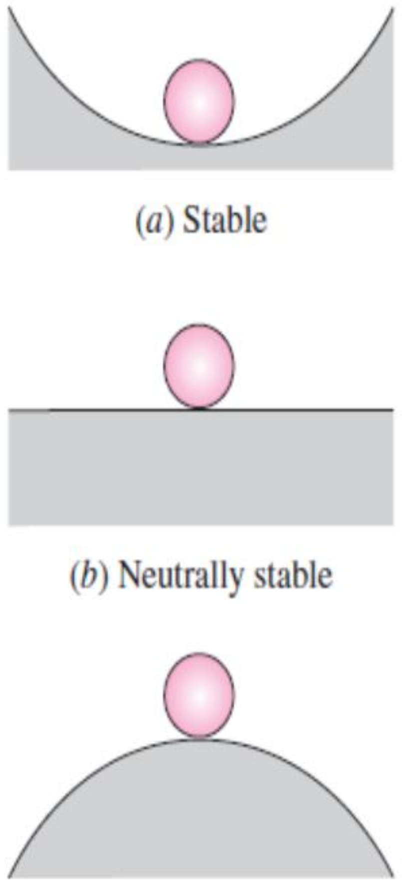
Forces on an immersed cube

Stability

STABLE since any small disturbance (someone moves the ball to the right or left) generates a restoring force (due to gravity) that returns it to its initial position.

NEUTRALLY STABLE because if someone moves the ball to the right or left, it would stay put at its new location. It has no tendency to move back to its original location, nor does it continue to move away.

UNSTABLE since any disturbance, even an infinitesimal one, causes the ball to roll off the hill – it does not return to its original position; rather it diverges from it.



(*a*) Stable

(*b*) Neutrally stable

(*c*) Unstable

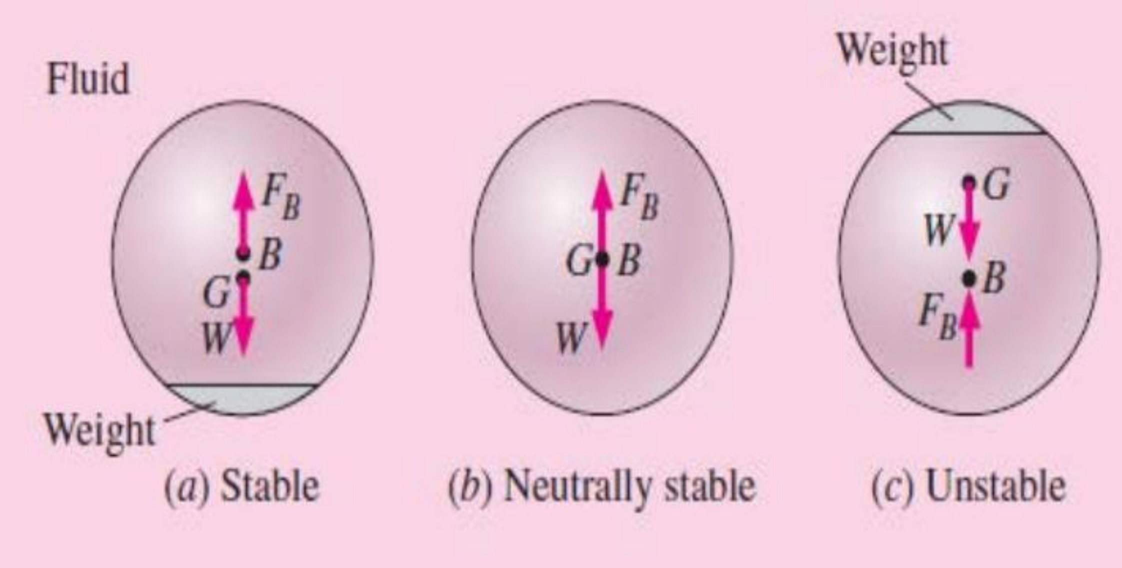
Stability of Immersed Bodies

PANA ACADEMY

STABLE: Center of buoyancy higher than CG of object

UNSTABLE: Center of buoyancy higher than CG of object.

NEUTRALLY STABLE: Center of buoyancy higher than CG of object.

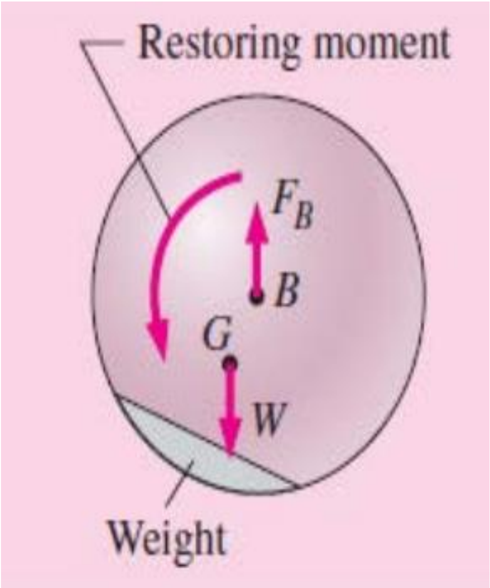


Stability of Immersed Bodies

STABLE: Center of buoyancy higher than CG of object

UNSTABLE: Center of buoyancy higher than CG of object.

NEUTRALLY STABLE: Center of buoyancy higher than CG of object.



Stability of floating Bodies

PANA ACADEMY

A measure of stability is the metacentric height GM, the distance between G and the metacenter M

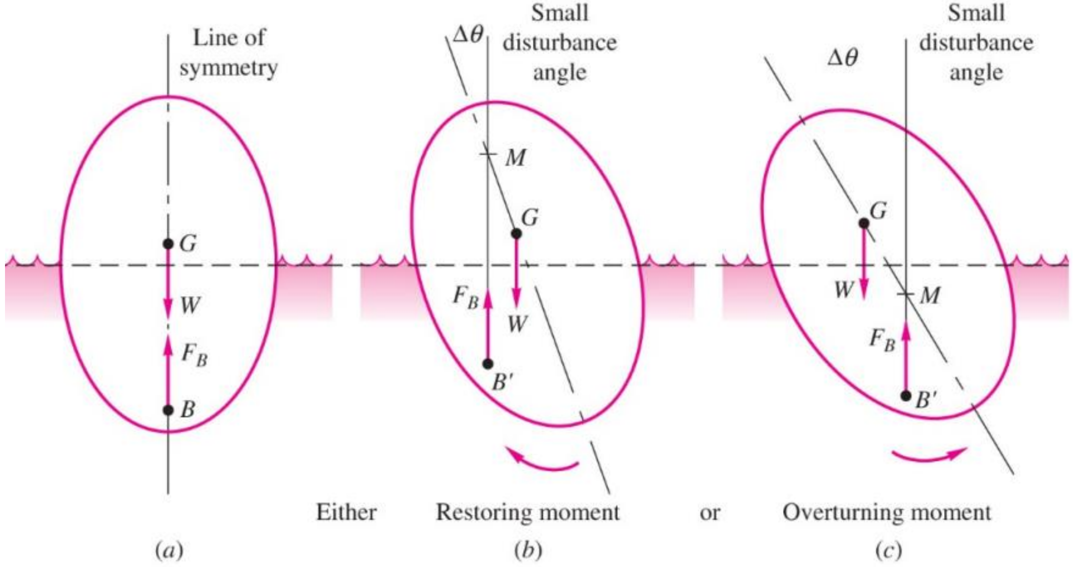
GM = BM – BG

$$BM = \frac{I}{V_{dis}}$$

STABLE: if M is above G (GM > 0)

UNSTABLE: if M is below G (GM < 0

NEUTRALLY STABLE: if M coincides G (GM = 0)



Stability of floating Bodies

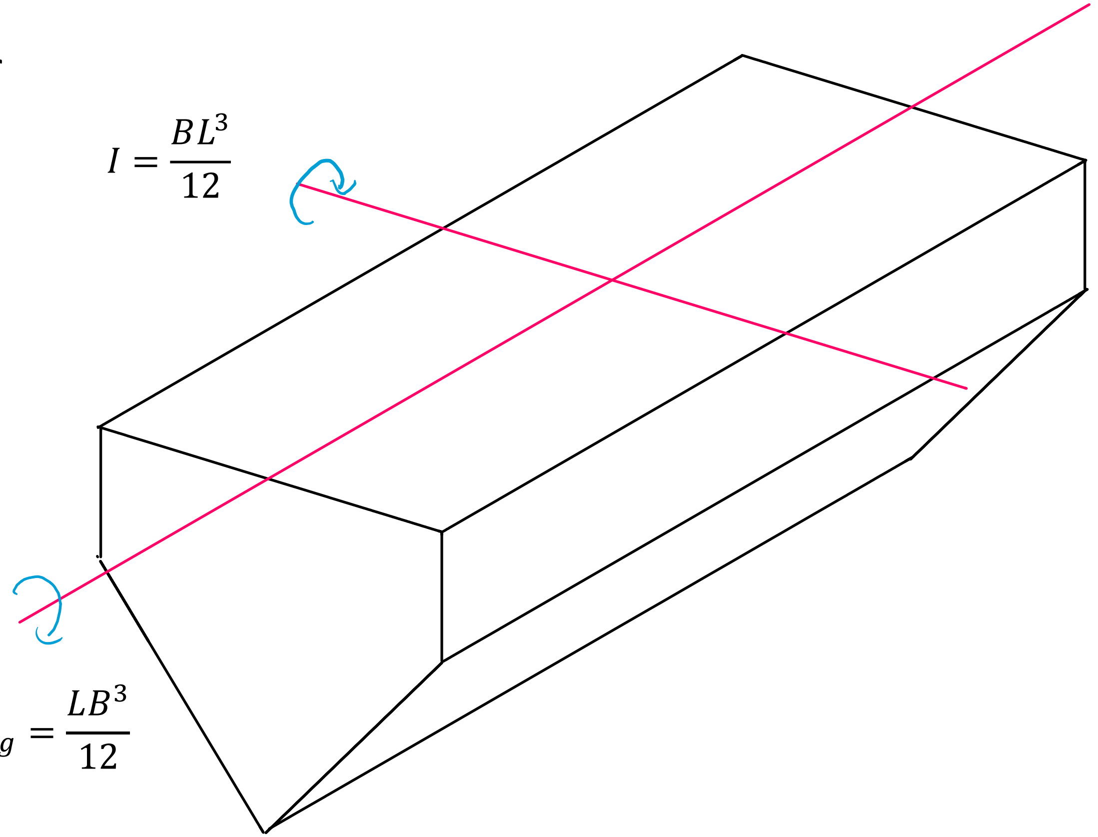
PANA ACADEMY

A measure of stability is the metacentric height GM, the distance between G and the metacenter M

GM = BM – BG

$$BM = \frac{I}{V_{dis}}$$

$$I = \frac{BL^3}{12}$$



$$I_{rolling} = \frac{LB^3}{12}$$

PANA ACADEMY

Thank YOU !!!