

4.5 Real-Time operating and Control System (ACtE0405)

Operating System Basics

1. Which of the following is not a function of an operating system?
 - a) Memory Management
 - b) Process Management
 - c) Web Browsing
 - d) File System Management
2. The operating system acts as an interface between:
 - a) User and software
 - b) Software and hardware
 - c) User and hardware
 - d) All of the above
3. Which component of the OS is responsible for managing memory allocation?
 - a) Kernel
 - b) CPU
 - c) Memory Manager
 - d) File System Manager
4. The core of an operating system is:
 - a) Shell
 - b) Command interpreter
 - c) Kernel
 - d) Application program
5. Which type of OS allows multiple users to interact with the computer at the same time?
 - a) Single-user OS
 - b) Multi-user OS
 - c) Batch OS
 - d) Real-time OS
6. Which of the following is a real-time operating system?
 - a) Linux
 - b) Windows
 - c) RTOS
 - d) Unix
7. The command line interface (CLI) is a type of:
 - a) GUI
 - b) Shell
 - c) Kernel
 - d) Memory manager
8. Which of the following is a function of the operating system?
 - a) Virus protection
 - b) Text editing
 - c) I/O Management
 - d) Data compression

Task, Process, and Threads

9. A process in execution refers to:
- a) A task
 - b) A program
 - c) An application
 - d) An OS
10. Which of the following is true about processes?
- a) Processes do not require memory.
 - b) Processes share memory by default.
 - c) Each process has its own memory space.
 - d) Processes are independent of each other.
11. A thread is also called a:
- a) Process
 - b) Lightweight process
 - c) Heavyweight process
 - d) Program
12. Which of the following is shared among threads in the same process?
- a) Stack
 - b) Registers
 - c) Program counter
 - d) Memory space
13. The unique identifier for a process is called its:
- a) Process handle
 - b) Process ID (PID)
 - c) Thread ID
 - d) System ID
14. Which of the following is true about user-level threads?
- a) They are managed by the kernel.
 - b) They are faster to create than kernel threads.
 - c) They cannot be created by the user.
 - d) They use more resources than kernel threads.
15. The state of a process is defined by:
- a) Its memory usage
 - b) The activity of its threads
 - c) Its execution context (e.g., registers, program counter)
 - d) The number of open files
16. Which of the following is a benefit of using threads?
- a) Simplifies memory management
 - b) Increases parallelism
 - c) Reduces the complexity of process scheduling
 - d) Improves single-threaded performance
17. Which of the following is a valid state for a process?
- a) Running, Waiting, Terminated
 - b) New, Running, Sleeping
 - c) Active, Suspended, Waiting

- d) Initializing, Running, Waiting
18. When a process creates a new process, the new process is called:
- a) Parent process
 - b) Child process
 - c) Thread
 - d) Clone
19. Which of the following is not true about kernel-level threads?
- a) They are slower to create compared to user-level threads.
 - b) They are managed by the operating system kernel.
 - c) They cannot be preempted.
 - d) They can run on different processors in a multi-core system.
20. Context switching is:
- a) Saving the state of one process and loading the state of another.
 - b) The process of switching from one OS to another.
 - c) Moving data from the CPU to memory.
 - d) A method of deadlock prevention.

Task Scheduling

21. Which scheduling algorithm assigns the CPU to the process that arrives first?
- a) Round Robin
 - b) Priority Scheduling
 - c) Shortest Job Next
 - d) First-Come, First-Served
22. In which scheduling algorithm does each process get a fixed time slice?
- a) Priority Scheduling
 - b) Round Robin
 - c) Multilevel Queue Scheduling
 - d) Shortest Job Next
23. Which scheduling algorithm selects the process with the shortest execution time first?
- a) First-Come, First-Served
 - b) Shortest Job Next
 - c) Priority Scheduling
 - d) Round Robin
24. In priority scheduling, a process with higher priority:
- a) Always gets more CPU time.
 - b) Is executed before processes with lower priority.
 - c) Gets less CPU time.
 - d) Waits for processes with lower priority to finish.
25. The issue of starvation in scheduling can occur when:
- a) Processes are not given enough memory.
 - b) Lower-priority processes never get scheduled.
 - c) Processes get stuck in an infinite loop.
 - d) The system runs out of resources.
26. Which of the following scheduling algorithms can cause starvation?

- a) Round Robin
 - b) First-Come, First-Served
 - c) Priority Scheduling
 - d) Shortest Job First
27. Which scheduling policy is most suitable for time-sharing systems?
- a) First-Come, First-Served
 - b) Shortest Job First
 - c) Round Robin
 - d) Priority Scheduling
28. In a preemptive scheduling algorithm:
- a) A running process cannot be interrupted.
 - b) A running process can be preempted by a higher-priority process.
 - c) All processes are executed in the order they arrive.
 - d) Processes are executed based on their burst time.
29. Which of the following is true for non-preemptive scheduling?
- a) A process can be interrupted during execution.
 - b) A process holds the CPU until it completes or blocks.
 - c) Scheduling decisions are based on real-time constraints.
 - d) Higher-priority processes can interrupt running processes.
30. Which scheduling algorithm gives equal CPU time to all processes?
- a) First-Come, First-Served
 - b) Shortest Job First
 - c) Round Robin
 - d) Priority Scheduling
31. Which of the following scheduling algorithms is non-preemptive?
- a) Shortest Job First
 - b) Round Robin
 - c) Priority Scheduling
 - d) First-Come, First-Served

Task Synchronization

32. Task synchronization is essential in:
- a) Single-threaded applications
 - b) Multithreaded applications
 - c) Operating systems only
 - d) User-level applications only
33. Which of the following is used to ensure mutual exclusion?
- a) Semaphore
 - b) File system
 - c) CPU scheduling
 - d) Memory management
34. A critical section is:
- a) A part of the process that performs I/O operations.
 - b) A segment of code that accesses shared resources.
 - c) A part of the operating system that handles scheduling.

- d) An error in process execution.

35. A deadlock is:

- a) A situation where processes run in an infinite loop.
- b) A situation where two or more processes wait indefinitely for resources held by each other.
- c) A situation where the OS crashes due to memory overload.
- d) A situation where multiple processes share the same resources.

36. Which of the following is not a condition for deadlock?

- a) Mutual exclusion
- b) Hold and wait
- c) Preemption
- d) Circular wait

37. Which mechanism can be used to avoid deadlock?

- a) Process priority
- b) Resource allocation graph
- c) Scheduling algorithm
- d) File system

38. A semaphore is a synchronization tool used to:

- a) Control access to shared resources.
- b) Allocate memory to processes.
- c) Schedule CPU tasks.
- d) Manage I/O operations.

39. Which of the following can lead to a race condition?

- a) Improper synchronization
- b) Deadlock prevention
- c) Priority scheduling
- d) Round Robin scheduling

40. Which method is commonly used to avoid race conditions?

- a) Mutual exclusion
- b) Preemption
- c) Round Robin scheduling
- d) Memory segmentation

41. In the context of synchronization, the term "busy waiting" refers to:

- a) A process that waits for resources by continuously checking a condition.
- b) A process that is ready to run but waiting for the CPU.
- c) A thread that is waiting for a signal.
- d) A method to allocate memory to processes.

42. Deadlock can be avoided by:

- a) Implementing circular wait.
- b) Allocating all required resources at the start.
- c) Allowing preemption of resources.
- d) Using non-preemptive scheduling.