Computer Organization and Embedded System

Input-Output Organization and Multiprocessor (ACtE0403)

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4.3 Input-Output Organization and Multiprocessor(ACtE0403):

- Peripheral devices,
- I/O modules,
- Input-output interface,
- Modes of transfer
- Direct Memory access,

- > Multiprocessors,
- Interconnection Structure,
- Inter-processor Communication
- Inter-process synchronization

<u>Multiprocessors</u>

- > A multiprocessor system is an interconnection of two or more CPUs.
- Can be either a central processing unit (CPU) or an input-output processor (IOP).
- Multiprocessors are classified as Multiple Instruction Stream, multiple Data Stream (MIMD) systems
- Multiprocessor are classified by the way their memory is organized:
 - A multiprocessor system with common shared memory is classified as a shared-memory or **tightly coupled multiprocessor**.
 - Each processor element with its own private local memory is classified as a distributed-memory or **loosely coupled system**.

Interconnection Structures

- The components that form a multiprocessor system are CPUs, IOPs and a Memory Unit.
- The interconnection between the components can have different physical configurations, depending on the **number of transfer paths** that are available:
 - Between the processors and memory in a shared memory system
 - Among the **processing elements** in a loosely coupled system

Interconnection Structures

- There are several physical forms available for establishing an interconnection network.
 - Time-shared common bus
 - Multiport memory
 - Crossbar switch
 - Multistage switching network
 - Hypercube system

Time-shared common bus

A common-bus multiprocessor system consists of a number of processors connected through a common path to a memory unit.

Disadvantages:

- Only one processor can communicate with the memory or another processor at any given time.
- The total overall transfer rate within the system is limited by the speed of the single path

Time-shared common bus





Multiport Memory

- A multiport memory system employs separate buses between each memory module and each CPU.
- The module must have internal control logic to determine which port will have access to memory at any given time.
- Advantages: The high transfer rate can be achieved because of the multiple paths.
- Disadvantages: It requires expensive memory control logic and a large number of cables and connections

Multiport Memory



Crossbar Switch

- Consists of a number of cross-points that are placed at intersections between processor buses and memory module paths.
- The small square in each cross-point is a switch that determines the path from a processor to a memory module.
- Advantages: Supports simultaneous transfers from all memory modules
- Disadvantages: The hardware required to implement the switch can become quite large and complex.

Crossbar Switch



Multistage Switching Network

The basic component of a multistage network is a two-input, twooutput interchange switch



Multistage Switching Network

- Some request patterns cannot be connected simultaneously. i.e. any two sources cannot be connected simultaneously to destination.
- In a tightly coupled multiprocessor system, the source is a processor and the destination is a memory module.
 - Set up the path
 - Transfer the address into memory
 - Transfer the data
- In a loosely coupled multiprocessor system, both the source and destination are processing elements.

Hypercube System

- The hypercube multiprocessor structure is a loosely coupled system composed of N=2ⁿ processors interconnected in an n-dimensional binary cube.
- Each processor forms a node of the cube and each processor address differs from that of each of its n neighbours by exactly one bit position.
- Routing messages through an n-cube structure may take from one to n links from a source node to a destination node.
- A routing procedure can be developed by computing the exclusive-OR of the source node address with the destination node address.



Three-cube

- The various processors in a multiprocessor system must be provided with a facility for communicating with each other.
- A communication path can be established through a portion of memory or a common input-output channels.
- The sending processor structures a request, a message, or a procedure, and places it in the memory mailbox.
- A more efficient procedure is for the sending processor to alert the receiving processor directly by means of an **interrupt signal**.

- In Tightly Coupled System, the multiprocessor system may have other shared resources. e.g., a magnetic disk storage unit.
- To prevent conflicting use of shared resources by several processors there must be a provision for assigning resources to processors. i.e. operating system.
- There are three organizations that have been used in the design of operating system for multiprocessors:
 - master-slave configuration,
 - separate operating system,
 - distributed operating system.

- In a master-slave mode, one processor is master and always executes the operating system functions.
- In the separate operating system organization, each processor can execute the operating system routines it needs.
 - This organization is more suitable for loosely coupled systems.
- In the distributed operating system organization, the operating system routines are distributed among the available processors.
 - Each particular operating system function is assigned to only one processor at a time.

- In Loosely Coupled System, there is no shared memory for passing information.
- The communication between processors is by means of message passing through I/O channels.
- The communication is initiated by one processor calling a procedure that resides in the memory of the processor with which it wishes to communicate.
- The communication efficiency of the inter-processor network depends on the communication routing protocol, processor speed, data link speed and the topology of the network.

Inter-process Synchronization

- The instruction set of a multiprocessor contains basic instructions that are used to implement communication and synchronization between cooperating processes.
- Communication refers to the exchange of data between different processes.
- Synchronization refers to the special case where the data used to communicate between processors is control information.
- Synchronization is needed to enforce the correct sequence of processes and to ensure mutually exclusive access to shared writable data.

Inter-process Synchronization

- Mutual exclusion: This is necessary to protect data from being changed simultaneously by two or more processors.
- Critical section: It is a program sequence that must complete execution before another processor accesses the same shared resource.
- A binary variable called a semaphore is often used to indicate whether or not a processor is executing a critical section.

Thank You.